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TECHNICAL DATA

Motor			BEOGRAM 4000 type 5215
Wow and Flutter	DIN 45 500, Page 3		<± 0.05 % <± 0.025 %
Rumble	DIN 45 500, Page 3	А В	>42 dB >65 dB
Speed Control Range			>6%
Motor Speed			315/435 rpm
Motor Suspension Resonant Frequency and Weight			3.5 Hz hor., 5 Hz vert. 4.5 kg

Pick-up			
Frequency Response	DIN 45 500, Page 3	± 5 dB ± 2 dB	20 - 30,000 ± 2.5 dB 50 - 20,000 ± 1.5 dB
Channel Separation	DIN 45 500, Page 3	1000 Hz 500 - 6300 Hz	>25 dB >20 dB
Channel Matching	DIN 45 500, Page 3		< 1.5 dB
Output Voltage and Load		mV/cm/sec. music average	0.6 mV/47 kohms 3 mV/47 kohms
Intermodulation	DIN 45 500, Page 3		<1 %
Compliance	Stated value X 10 ⁻⁶ cm/dyn.		30
Stylus			Elliptical naked diamond 5 X 17 µ
Recommended, Stylus Pressure			1 gram
Stylus Pressure Range			0 - 1.5 gram
Maximum Tracking Angle Error	With optimal adjustment		0.04°
Arm Length, Suspension to Stylus			155 mm
Replacement Stylus Assembly			Complete cartridge type 8905428

Other Data	4.	
Power Supply		110, 130, 220,240 volts 50 - 60 Hz 40 watts
Dimensions		10 X 49 X 38 cm
Weight		12 kg

	BEOGRAM 4000 Type 5215
Speeds	33 - 45 rpm electronic section
Pickup-arm System	Tangential
Pickup Cartridge	SP 15
Automatic Record-size Scenning	Yes
Automatic Pickup- movement Control	Yes
Automatic Speed Selection	Yes
Cueing Control	Electronic air- pressure damped
Skating Compensation	Parallel tracking error angle compensated
Drive System	Belt
Motor	Synchronous electronically controlled
Vernier Speed Adjustment	Yes separately
Motor Suspension System	Leaf springs and pendulums
Turntable, Diameter and Weight	Zinc cast, diameter 300 mm 2.2 kg
Stroboscopic Scale	Light indicator 33 and 45 rpm 50 and 60 Hz
Dust Cover	Transparent, hinged and detachable
Meets DIN 45 500 Requirements	Yes

Subject to change without notice

DIAGRAM EXPLANATION

The electrical circuits are, concerning diagram, divided into two diagrams.

- 1. Control circuit (logic)
- 2. Power supply, indicator circuit, speed relais circuit, oscillator, lift circuit, motor control (servo), differential stop, detector circuit, etc.

The abbreviations used in connection with the common cable are the abbreviations of the functions in English. The outputs of the flip-flops are designated Q and Q

The stated voltages are positive in relation to chassis. They are measured with the detector arm above the ribs of the turntable with no record on and with a stationary pick-up arm.

ADSKILLELSE

DISASSEMBLY/ZERLEGUNG

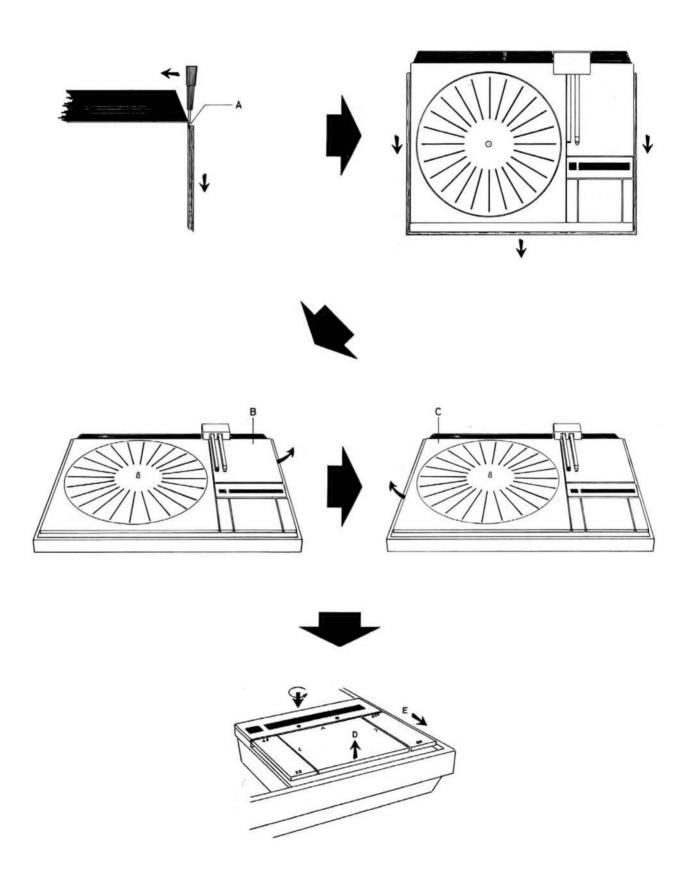
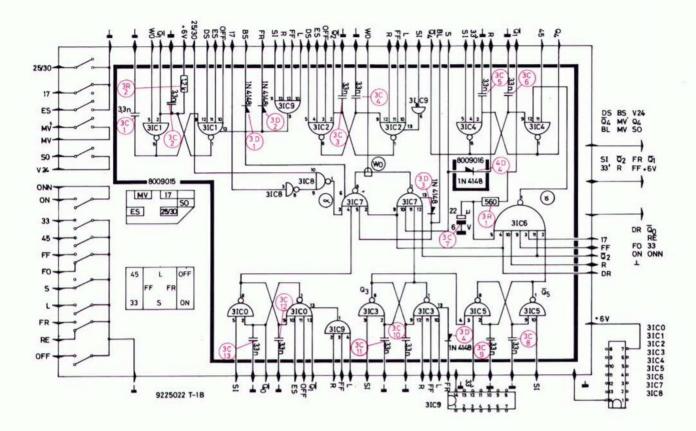
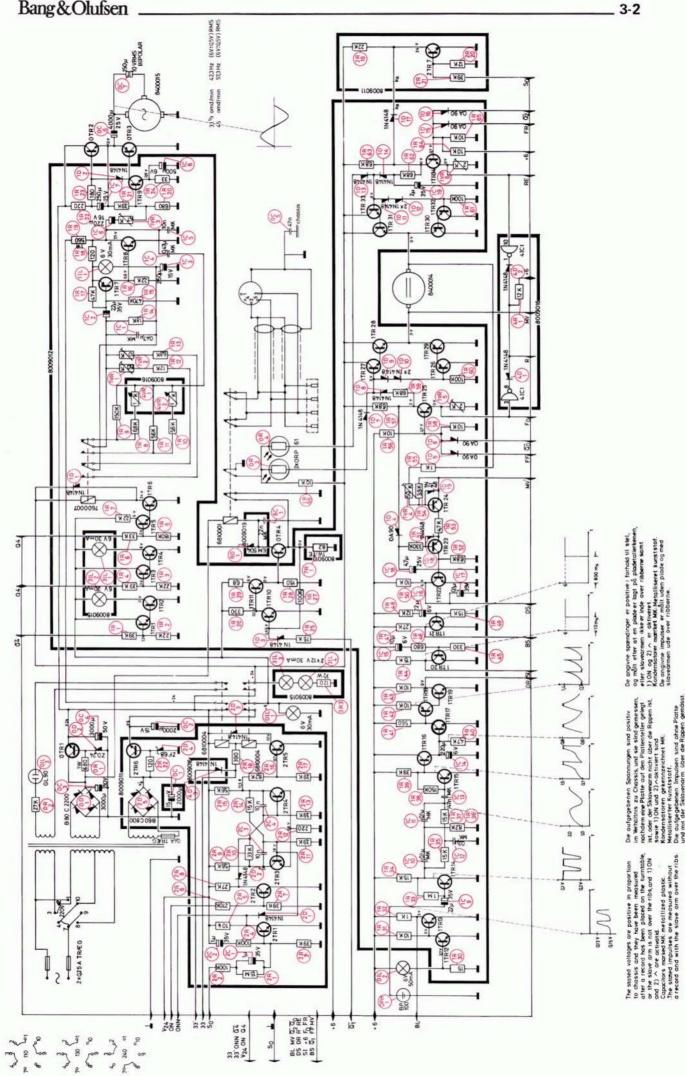


DIAGRAM 1



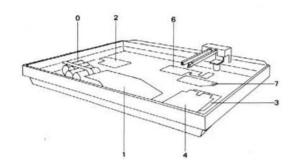
	INDEX	14131211 10 9 8 D 1 2 3 4 5 6 7	
3 IC 0			
3 IC 1			
3 IC 2	8340013	POUL 424	
3 IC 3		FCH 131	
3 IC 4			
3 IC 5			
3 IC 6	8340012	FCH 111	
3 IC 7	0210012	FOUL 121	
3 IC 8	8340013	FCH 131	
3 IC 9	8340011	FCY 101	
4 IC 1	8340013	FCH 131	



		B C E	C[I I]B	BCE.	E C B	E B	B c E
1TR1 1TR2 1TR3 1TR4 1TR5	8320095	BC 239 B BC 184 BK	BC 149 B		BC 169 B BC 184 BL	BC 109 B	
1TR6	8320097	BC 237 B BC 182 BK	BC 147 B		BC 167 B BC 182 BL	BC 107 B	
1TR7	8320161	BC 261 B			BC 212 BL	BC 251 B	
1TR8 1TR9	8320232					BC 142 BC 144	-
1TR10	8320095	BC 239 B BC 184 BK	BC 149 B		BC 169 B BC 184 BL	BC 109 B	
1TR11	8320232					BC 142 BC 144	
1TR12 1TR13 1TR14 1TR15 1TR16 1TR17	8320095	BC 239 B BC 184 BK	BC 149 B		BC 169 B BC 184 BL	BC 109 B	
1TR18	8320161	BC 261 B			BC 212 BL	BC 251 B	
1TR 19 1TR 20 1TR 21 1TR 22	8320095	BC 239 B BC 184 BK	BC 149 B		BC 169 B BC 184 BL	BC 109 B	
1TR23 1TR24	8320161	BC 261 B		16.45	* BC 212 BL	BC 251 B	
1TR25	8320097	BC 237 B BC 182 BK	BC 147 B		BC 167 B BC 182 BL	BC 107 B	
1TR26	8320161	BC 261 B	***		BC 212 BL	BC 251 B	
1TR27	8320097	BC 237 B BC 182 BK	BC 147 B	ī	BC 167 B BC 182 BL	BC 107 B	
1TR28/ 1TR29 1TR30/ 1TR31	8320135					BC 143/ BC 144 BC 143/ BC 142	
1TR32	8320161	BC 261 B			BC 212 BL	BC 251 B	
1TR33 1TR34 2TR1 2TR2 2TR3 2TR4 2TR5	8320097	BC 237 B BC 182 BK	BC 147 B		BC 547B BC 167B BC 182BL	BC 107 B	
2TR6	8320124					BC 119	
2TR7	8320097	BC 237 B BC 182 BK	BC 147 B		BC 167 B BC 182 BL	BC 107 B	
0TR1	8320103						2 N 5034
0TR2	8320266			TIP 31			
OTR3	8320265			TIP 32			
0TR4	8320312			TIP 41 A			

OPH1

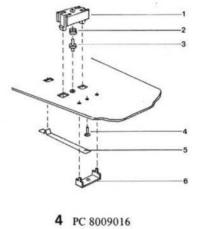
BP 100



	0	
Pos.	-	Index
	R	
OR1	680, 5 %, 1 W	5012011
OR2	27k, 10 %, 1/2 W	5001047
OR3	ORP 61	5210004
0R4	ORP 61	5210004
	c - -	
OC1	2000 μ, 15 V	4200265
OC2	2000 µ, 15 V	4200265
OC3	3000 μ, 50 V	4200258
0C4	3000 μ, 50 V	4200258
OC5	47 n, 10 %, 250 V	4130087
0C6	4000 μ, 25 V	4200259
0C7	150 μ, 10 VRMS, BIPOLAR	4200260
	D —	
0D1	B80C2200	8310020
0D2	24 V, 5 %, 1,3 W	8300160
	TR -	
OTR1	4	8320103
OTR2		8320266
OTR3		8320265
0TR4		8320312
	IL -	
OIL1	6 V, 30 mA	8230025
OIL2	6 V, 50 mA	8230020
OIL3	GL 90	8230038
	м -(\overline{\o	
OM 1	6 V, AC	8400015
0M2	12 V, DC	8400014
	MS -	
OMS1	**	6810001
	DIT -	

	7	PC 8009010	
Pos.	Plac.		Index
		R	
7R1	A1	8,2, TE, 5 %, 1 W	5100082

Pos.	25/30	17	ES	MV	so
1	3152068	3152068	3152068	3152068	3152068
2		2812041			
3	7500060	7500067	7500060	7500060	7500060
4		2364024			
5	7500051	7500051	7500051	7500051	7500051
6	7500050		7500050	7500050	7500050

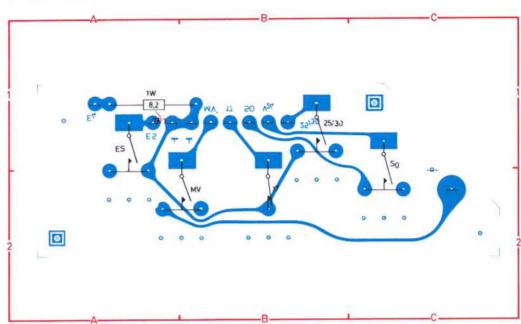


		323	6
	4	PC 8009016	
Pos.	Plac.		Index
		R	
4R 1	C2	12 k, 5 %, 1/8 W	5010046
		VR -	
4VR1	B3	1 k, LIN, 0,15 W	5300079
4VR2	C3	1 k, LIN, 0,15 W	5300079
		D —	
4D 1	B2	1N4148, SFD 184	8300058
4D 2	B2	1N4148, SFD 184	8300058
4D 3	A1	1N4148, SFD 184	8300058
4D 4	B1	1N4148, SFD 184	8300058
		IC IC	
4IC1	B2	FCH131	8340013

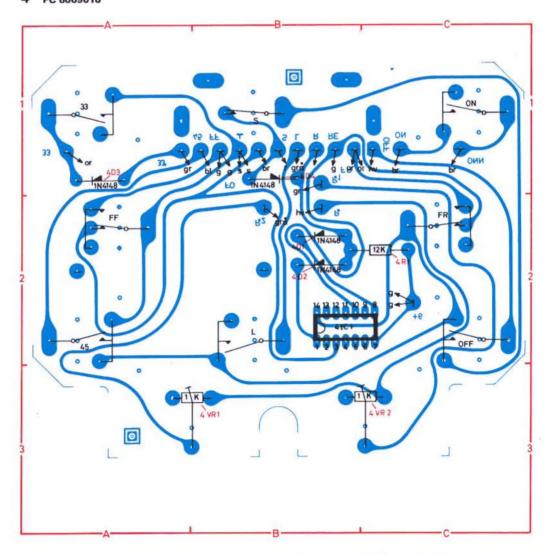
Pos.	33	FF	45	S	L	ON	FR	OFF
1	3152068	3152068	3152068	3152068	3152068	3152068	3152068	3152068
2								
3	7500059	7500066	7500059	7500059	7500059	7500059	7500066	7500059
4		2364024		2364024			2364024	
5	7500051	7500051	7500051	7500051	7500051	7500051	7500051	7500051
6	7500061	7500050	7500061		7500061	7500061	7500050	7500061

BEOGRAM 4000, TYPE 5215 Correct on page 3-4

7 PC 8009010



4 PC 8009016



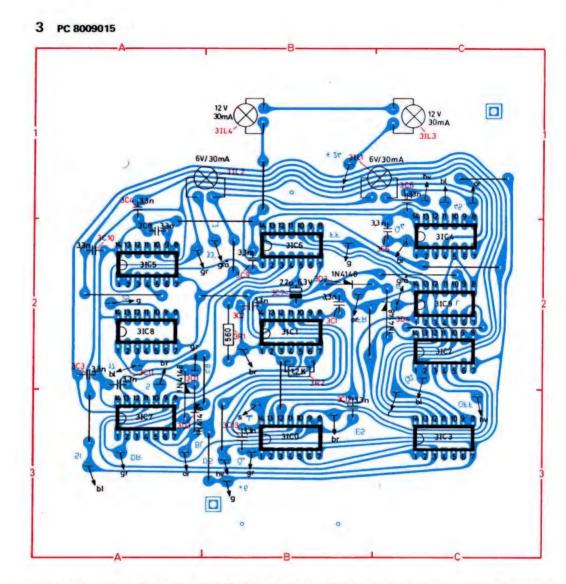
D EM 504, 1N4004

A1

6D1

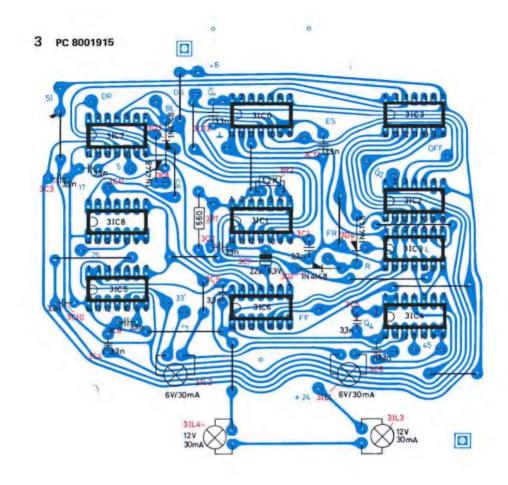
Plac. R ——— R R ——— R R ——— R R R ——— R R R R					Do	ar 46	,	~				11	-																				_ `
Proceedings	į	Index	5010093 5010049	5010060	5010059	5010060	5010141	5010075	5010069	5010092	5010069	5010053	5010154	5010069	5010079	5010046	5010060		1301057	4201057	4010041		8300058	8300058	8300154 8300155	8320097 8320097 8320097 8320097 8320097	8320124 8320097	6810004 6810004		7600013 7600013		Index	4130096
Proceedings	PC 8009011		1,5 M, 10 %, 1/8 W 100 k, 5 %, 1/8 W	39 k, 5 %, 1/8 W 100 k, 5 %, 1/8 W	10 k, 5 %, 1/8 W	39 k, 5 %, 1/8 W	27 K. 5 %. 1/8 W	33 k. 5 %, 1/8 W	3,9 k, 5 %, 1/8 W	220, 5 %, 1/8 W	3.9 k, 5 %, 1/8 W	5.6 k. 5 %, 1/8 W	8.2 k. 5 %, 1/8 W	3.9 k, 5 %, 1/8 W	390, 5 %, 1/8 W	12 k, 5 %, 1/8 W	39 k, 5 %, 1/8 W 120, 5 %, 1/8 W	. 	V 36.4.	1 u/35 V	10n/40 V	1	1N4148, SFD 184	1N4148, SFD 184 1N4148, SFD 184	6,8 V B80C800				[]		PC 8009019		-
P. 600019	7																				B2					B2 B2 A2 A2	B 11	A1 A1		A1 A1			V IV
FC 8000019	4	Pos.						2R10	2R11	2R12	2R13	2R14	2R16	2R17	2K18	2R20	2R21 2R22									2TR1 2TR2 2TR3 2TR4 2TR5	2TR6 2TR7	2MS1 2MS2		2MS1 2MS2		Pos.	139
PC 8009019 PC 8009019					8320095	8320095	8320095	8320095	8320095	8320095	8320095	8320095	8320095	8320161	8320097	8320161	8320135	8120115	6320133	8320097	8320097							1		~~~			
PC 8008019 PC 8008019							10	D2	10	2 2			A3	A3	A3	A2			A2	A2 A2	B2									1	(Sec)		
PC 8009019					ITR12	ITR13	ITRIS	ITR16	ITR17	1TR19	1TR20	ITR21	1TR 22	11R23	ITR25	ITR26	ITR 28	1TR30	ITR31	11K32 1TR33	1TR34									100	S PAGE		Q
			B 178	00 F 1					-		区 中	1000年日 日本日本日本日本日本日本日本日本日本日本日本日本日本日本日本日本日本日本日	1000000000000000000000000000000000000		1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0			N A	42 A 250V	200	81	vi est		-		•	35. 3-100 O				w000189		Α

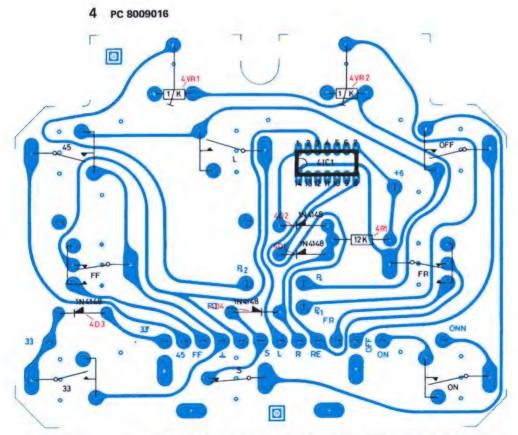
1	PC 80	09012				VR -₩	
_	ъ.		Indon	1VR1	E1	50 k, 20 %	5370061
Pos.	Plac.		Index	1VR1 1VR2	E2	4,7 k, 20 %	5370051
		R□-		1VR3	E1	4,7 k, 20 %	5370058
4 D 4			5010060	1VR4	E1	50 k, 20 %	5370061
1R1	C2	39 k, 5 %, 1/8 W	5010060 5010079	1VR5	El	2 k, 20 %	5370006
1R2 1R3	C2 C2	22 k, 5 %, 1/8 W 22 k, 5 %, 1/8 W	5010079	1VR6	E1	2k, 20 %	5370006
1R3	C1	39 k, 5%, 1/8 W	5010060				
1R5	B3	180 k, 5 %, 1/8 W	5010072			c - -	
1R6	C2	33 k, 5 %, 1/8 W	5010075	1C 1	C2	0,47 µ, 250 V, 10 %	4130029
1R7	C2	2,2 k, 5 %, 1/8 W	5010064	1C 2	D2	2,2 µ, 35 V	4201069
1R8	C3	6,8 k, 5 %, 1/8 W	5010052	1C 3	D2	220 μ, 16 V	4200097
1R9	C3	150 k, 5 %, 1/8 W	5010063	1C 4	D3	0,47 µ, 250 V, 10 %	4130029
1R10	C3	5,6 k, 5 %, 1/8 W	5010041	1C 5	E2	10 n, 250 V, 20 %	4130081
1R11	C3	56k, 5 %, 1/8 W	5010061	1C 6	E2	220 µ, 16 V	4200097
1R12	E1	22 k, 5 %, 1/8 W	5010079	1C 7	E2	220 μ, 16 V	4200097 4200109
1R13 1R14	E2 D2	10 k, 5 %, 1/8 W 15 k, 5 %, 1/8 W	5010059 5010053	1C 8 1C 9	E2 B1	470 μ, 6 V 2,2 μ, 35 V	420109
1R14	D2	470 k, 5 %, 1/8 W	5010077	1C10	DI	0,1 μ, 250 V, 20 %	4130075
1R16	D2	2,2 k, 5 %, 1/8 W	5010064	1C11	D1	0,1 μ, 250 V, 20 %	4130075
1R17	D2	47 k, 5 %, 1/8 W	5010045	1C12	D1	0,22 µ, 250 V, 20 %	4130082
1R18	D3	120, 5 %, 1/8 W	5010128	1C13	D1	47 n, 250 V, 20 %	4130078
1R19	D2	560, 10 %, 1 W	5002022	1C14	D 1	220 μ, 16 V	4200097
1R20	E2	680, 5 %, 1/8 W	5010144	1C15	C2	10 μ, 6 V	4200101
1R21	E2	3,9 k, 5 %, 1/8 W	5010069	1C16	C2	22 μ, 6 V	4200218
1R22	D2	220, 5 %, 1/8 W	5010092	1C17	B2	0,1 μ, 35 V	4200169
1R23	E3	180, 5 %, 1/8 W	5010362	1C18 1C19	A3 A2	4,7 μ, 25 V 2,2 μ, 35 V	4200108 4201069
1R24	E2	33, 5 %, 1/8 W	5010253 5010053	1019	AZ	2,2 μ, 33 γ	4201009
1R25 1R26	B3 B2	15 k, 5 %, 1/8 W 330, 5 %, 1/8 W	5010033			RL	
1R20	C2	100 k, 5 %, 1/8 W	5010049				
1R28	B3	150, 5 %, 1/8 W	5010057	1RL1	D1	24 V	7600007
1R29	B2	6,8, 10 %, 1/2 W	5000111			\bigcirc	
1R30	В3	15, 5 %, 1/8 W	5010468			IL -(X)-	
1R31	D2	10 k, 5 %, 1/8 W	5010059	1IL1	C3	6 V, 30 mA	8230041
1R32	D2	1 k, 5 %, 1/8 W	5010040				
1R33	C1	1 M, 5 %, 1/8 W	5010054			D +	
1R34	Cl	15 k, 5 %, 1/8 W	5010053	1D 1	В3	1N4148, SFD 184	8300058
1R35	C1	15 k, 5 %, 1/8 W	5010053 5010154	1D 1 1D 2	E2	1N4148, SFD 184	8300058
1R36 1R37	C1 D1	8,2 k, 5 %, 1/8 W 15 k, 5 %, 1/8 W	5010053	1D 3	B3	1N4148, SFD 184	8300058
1R38	D1	150 k, 5 %, 1/8 W	5010063	1D 4	A3	OA90	8300009
1R39	D2	39 k, 5 %, 1/8 W	5010060	1D 5	A3	OA90	8300009
1R40	D1	4,7 k, 5 %, 1/8 W	5010048	1D 6	A3	OA90	8300009
1R41	D2	10 k, 5 %, 1/8 W	5010059	1D 7	A3	1N4148, SFD 184	8300058
1R42	E1	10 k, 5 %, 1/8 W	5010059	1D 8	A3	1N4148, SFD 184	8300058
1R43	E1	10 k, 5 %, 1/8 W	5010059	1D 9	A3	1N4148, SFD 184	8300058
1R44	C1	1,5 k, 5 %, 1/8 W	5010247 5010044	1D10 1D11	A2 A2	1N4148, SFD 184 1N4148, SFD 184	8300058 8300058
1R45	C1 C1	330, 5 %, 1/8 W 680, 5 %, 1/8 W	5010144	1D11 1D12	A2	1N4148, SFD 184	8300058
1R46 1R47	C2	27 k, 5 %, 1/8 W	5010141	1D12	A2	1N4148, SFD 184	8300058
1R48	C2	12 k, 5 %, 1/8 W	5010046	1D14	A2	1N4148, SFD 184	8300058
1R49	C2	15 k, 5 %, 1/8 W	5010053	1D15	B2	OA90	8300009
1R50	B2	10 k, 5 %, 1/8 W	5010059	1D16	B2	OA90	8300009
1R51	A3	330 k, 5 %, 1/8 W	5010117	1D17	B2	1N4148, SFD 184	8300058
1R52	A3	6,8 k, 5 %, 1/8 W	5010052	1D18	A3	1N4148, SFD 184	8300058
1R53	A3	4,7 k, 5 %, 1/8 W	5010048	1D19	B3	1N4148, SFD 184	8300058
1R54	B3	3,9 k, 5 %, 1/8 W	5010069				
1R55	A2	1 k, 5 %, 1/8 W	5010040 5010059			TR -	
1R56	B2 A3	10 k, 5 %, 1/8 W 6,8 k, 5 %, 1/8 W	5010052			4	
1R57 1R58	A3	10 k, 5 %, 1/8 W	5010052	1TR 1		8320095	
1R59	B3	68 k, 5 %, 1/8 W	5010062	1TR 2		8320095	
1R60	A2	100 k, 5 %, 1/8 W	5010049	1TR 3		8320095	
1R61	A2	100 k, 5 %, 1/8 W	5010049	1TR 4		8320095	
1R62	B2	68 k, 5 %, 1/8 W	5010062	1TR 5 1TR 6		8320095 8320097	
1R63	B2	6,8 k, 5 %, 1/8 W	5010052	1TR 0		8320161	
1R64	B2	10 k, 5 %, 1/8 W	5010059	1TR 8		8320232	
1R65	A2	10 k, 5 %, 1/8 W	5010059	1TR 9		8320232	
				1TR10		8320095	
		•		٠,٠			



SET FRA KOMPONENTSIDE / SEEN FROM COMPONENT SIDE / VON DER BAUTEILSEITE AUS GESEHEN

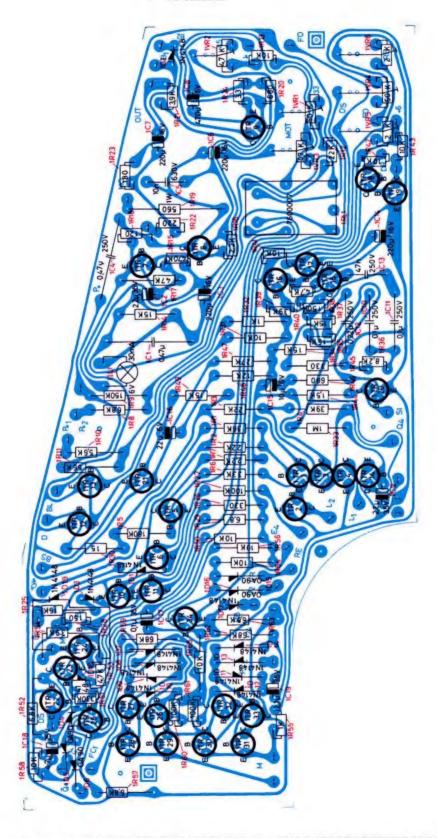
	3	PC 8009015		
Pos.	Plac.		Index	
		R		IC IC
3R 1	B2	560, 5 %, 1/8 W	5010067	3IC0 B3 FCH131 8340013
3R 2	B2	1,2 k, 5 %, 1/8 W	5010153	3IC1 B2 FCH131 8340013
				3IC2 C2 FCH131 8340013
		c +		3IC3 C3 FCH131 8340013
3C 1	B2	3,3 n, 100 V, 10 %	4011025	3IC4 C2 FCH131 8340013
3C 2	B2	3,3 n, 100 V, 10 %	4011025	3IC5 A2 FCH131 8340013
3C 3	A2	3,3 n, 100 V, 10 %	4011025	3IC6 B2 FCH111 8340012
3C 4	Al	3,3 n, 100 V, 10 %	4011025	3IC7 A3 FCH131 8340013
3C 5	C2	3,3 n, 100 V, 10 %	4011025	3IC8 A2 FCH131 8340013
3C 6	CI	3,3 n, 100 V, 10 %	4011025	3IC9 C2 FCY101 8340011
3C 7	B2	22 μ/6,3 V	4200218	\bigcirc
3C 8	A2	3,3 n, 100 V, 10 %	4011025	IL -(X)-
3C 9	B2	3,3 n, 100 V, 10 %	4011025	3IL1 B1 6 V, 30 mA 8230041
3C10	A2	3,3 n, 100 V, 10 %	4011025	3IL2 B1 6 V, 30 mA 8230041
3C11	A2	3,3 n, 100 V, 10 %	4011025	3IL3 C1 12 V, 30 mA 8230040
3C12	B3	3,3 n, 100 V, 10 %	4011025	2IL4 B1 12 V, 30 mA 8230040
3C13	В3	3,3 n, 100 V, 10 %	4011025	
		D —		BEOGRAM 4000, TYPE 5215
3D 1	A2	1N4148, SFD 184	8300058	Correct on page 3-8
3D 2	B2	1N4148, SFD 184	8300058	Correct on page 5-6
3D 3	A3	1N4148, SFD 184	8300058	211.2 61 241/26 1 222224
3D 4	C2	1N4148, SFD 184	8300058	3IL3 C1 24V/25mA 8230044
30 4	02	1117170, 31 1/ 104	0300030	3IL4 B1 24V/25mA 8230044

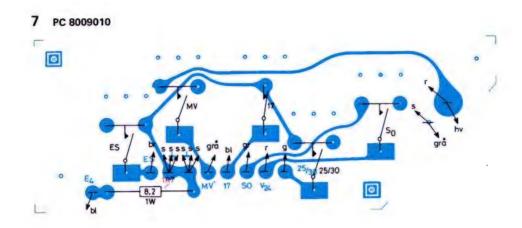


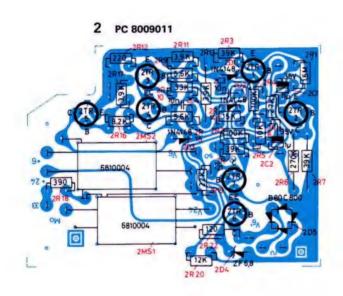


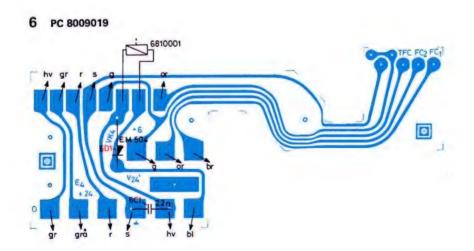
SET FRA PRINTSIDE / SEEN FROM CONDUCTOR SIDE / VON DER LEITERSEITE AUS GESEHEN

1 PC 8009012



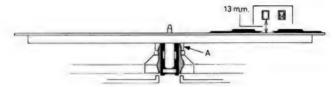






MECHANICAL ADJUSTMENTS

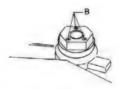
Height Adjustment of Turntable



Loosen nut A at the turntable bearing and adjust the height of the bearing so that the spacing between the turntable and the detector arm is 13 mm.

Tighten nut A lightly.

Vertical Adjustment of Turntable Bearing



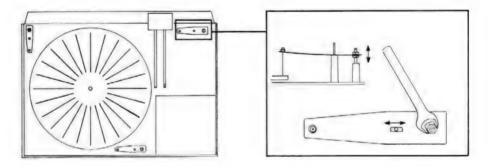
Turn the transit screws to lock the floating chassis.

With screws B adjust the turntable bearing so that it is at right angles to the chassis — in other words so that the turntable surface is parallel with the cover plate.

Check height adjustment (13 mm) at both the rim and centre of the turntable.

Height and Side Adjustment of Chassis

Loosen transit screws so that chassis floats freely.



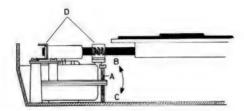
With the suspension springs adjust the chassis so that the turntable is flush with the cover plate and so that the chassis is centered with respect to the transit screws.



Also slide the springs backwards and forwards to locate the turntable centrally in the cutout in the cover plate.

To make this adjustment loosen the top nuts and thereafter adjust the screw to the desired height and slide the springs to the desired position. Thereafter retighten the nuts.

Adjustment of Belt Drive



Adjust the belt so that it runs on the middle of the pulley and the belt face on the turntable.

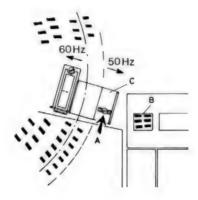
To shift the belt farther down on the pulley, turn screw A so that the motor tilts in the direction of arrow B.

To shift the belt farther upwards, loosen screw A and bend the motor suspension in the direction of arrow C. Thereafter tighten screw A until the belt runs on the middle of the pulley.

Adjust belt guides D so that they prevent the belt from running upwards or downwards off the pulley and so that they do not touch the belt during operation.

NOTE: The belt must be placed so that its ground (rough) side faces the pulley and turntable.

Adjustment of Stroboscope



Loosen screw A.

Adjust bracket C with the mirror so that the stroboscope image is located in the middle of the field of vision.

Tighten screw A.

NOTE: The two outer rows are for 50 Hz and the two inner ones are for 60 Hz.

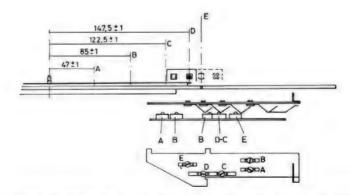
Adjustment of Slide Contact Springs

Height



Adjust all contact springs so that they only just actuate the contacts but also so that they do not jam against the contact pins, thus obstructing the slide transport.

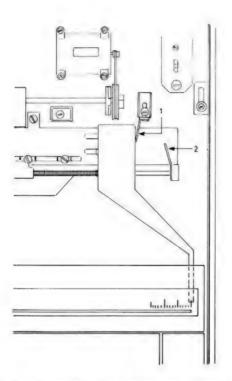
Placement



Adjust the horizontal placement of the springs so that, during slide transport, they will actuate their respective contacts when the pickup is spaced from the middle of the record spindle by the amount indicated in the sketch.

To adjust, loosen the screws holding the single spring and slide it in the oblong hole.

Adjustment of Dial Pointer



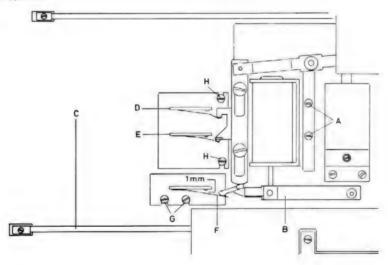
Zero Adjustment

Zero adjustment is performed by bending the tag 1 with the slide in its extreme right-hand position.

Start Adjustment

Adjust (bend) angle 2 so that the pointer begins to move away from "0" when the pickup lowers into the first groove of a 30 cm record.

Adjustment of Magnet Coil System



Magnet Coil

Loosen screws A.

Slide the magnet coil to the place where the arm B is parallel with tie-bar C when the magnet coil armature has been pulled home.

Tighten screws A.

Contacts F

Contacts F, which cut in the power limiter circuit, should be adjusted so that they are spaced 0.5 - 1, with the magnet coil armature pulled home.

To adjust, loosen screws G.

Contacts D and E

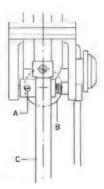
Contacts F and G should be adjusted so that the contact functions are not performed until the pickup stylus is in contact with the record but on the other hand as quickly as possible after the stylus hits the record.

Moreover, contacts E, of the duplex type, should be adjusted so that the upper contacts break first and the lower ones immediately afterwards.

Contacts D turn on the servo mechanism. Contacts E connect the pickup signal leads together and short-circuit them.

Adjustment of Pickup Arm System

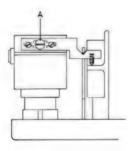
Horizontal Placement (Fixing)



Place the pickup arm in a bearing frame so that the centre line C of the pickup arm is located on the centre line of the shaft B with an accuracy of ± 0.2 mm.

To make the adjustment, loosen screw A and slide the pickup arm in one direction or the other, thereafter retightening screw A.

Static Balance

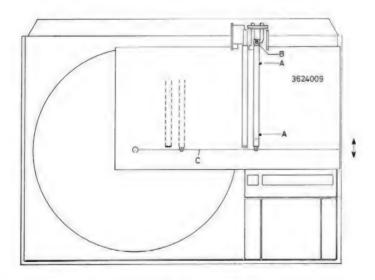


Set stylus adjustment to "0".

Release pickup arm from lifting arm.

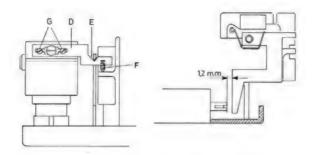
Adjust screw A until balance is obtained in the system.

Length, Height and Parallel Adjustment



Adjust stylus force to 1 gr. Take off turntable. Run pickup arm in towards the centre.

Mount tool 3624009 on the Beogram 4000 as shown by sketch. Run pickup arm out close to pins A. Lower pickup on to tool. Slide tool backwards or forwards so that stylus drops into groove C. Keep tool fixed in this position. Raise pickup and run it towards the centre. Lower pickup into the position shown in the sketch. If the stylus hits outside groove C, adjust screw B so that the deviation in question is halved. Run the pickup arm all the way out close to pins A. At this point lower the pickup and slide tool 3624009 so that the stylus is exactly in groove C. Raise the arm and now check if the arm is equally spaced from the pins A. Also make sure that the lifting arm rests in the bottom of the V-notch E on the arm D.



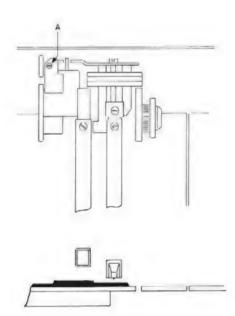
If the pickup arm is not parallel with the line between pins A, loosen screws G and slide arm D backwards or forwards until parallelism has been accomplished (the lifting arm must be in the bottom of the V-notch during this adjustment).

NOTE: Length adjustment of the pickup arm should be checked after adjustment of the arm D.

Adjust screw F so that the arm is horizontal (reference to detector arm) and so that the lifting arm is spaced 1.2 mm \pm 0.3 mm from the damper cylinder as shown by the sketch. It may be necessary to tilt the arm D when making this adjustment.

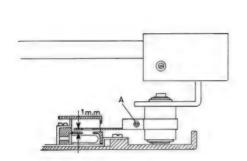
NOTE: If the arm D is to be tilted, the parallel adjustment of the pickup arm must be checked and repeated if necessary. Check static balance and readjust if necessary.

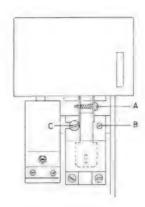
Lowering (Depth) Adjustment



Adjust screw A with the pickup arm lowered so that the stylus clears the low portions of the turntable ribs (by approx. 0.5 mm).

Adjustment of Diaphragm





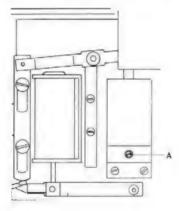
The diaphragm is adjusted by loosening screw A and turning and sliding it on the arm bearing.

Adjustment should be made so that the 1 mm spacing shown is complied with and so that the diaphragm arm becomes parallel with the pickup arm.

Fine adjustment of the diaphragm is performed with a record placed on the turntable and the drive belt removed.

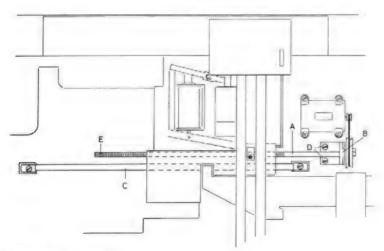
- 1: Run arm in over record.
- 2: Lower pickup.
- 3: Turn turntable by hand, checking that first operation of servo system occurs after 4 ± 1 turns and thereafter at every turn.
- 4: If the servo system does not operate within 4 ± 1 turns, loosen screw C and adjust eccentric B. Thereafter raise the arm and repeat items 2 4.
- 5: After adjustment of eccentric B, screw C should be tightened.
- 6: Make sure that the servo system does not regulate backwards until after the turntable has turned at least 10 cm backwards from the forwards regulation. To make adjustment if necessary, correct the spacing (1 mm) between the diaphragm and the photoresistor.

Adjustment of Damper Cylinder



Adjust valve A so that pickup lowers in between 1 and 1.5 sec.

Adjustment of Spindle



Adjust spindle A so that it is parallel with tie-bar C.

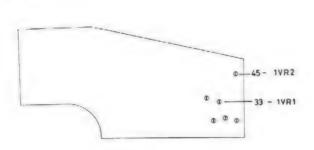
To adjust, loosen screws D and turn cap B.

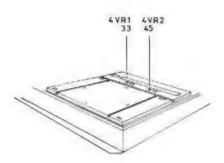
Best parallelism is obtained when spindle Λ has minimum eccentricity at E during operation.

ELECTRICAL ADJUSTMENTS

Remove Beogram 4000 cover plates (see Disassembly).

Speed Adjustment

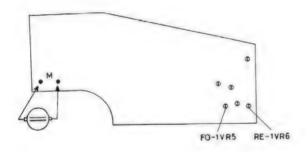


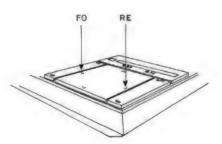


Connect the instrument to the mains. Press On and thereafter LIFT so that the pickup arm is stationary and the turntable is rotating. Set 33 r.p.m. potentiometer 4VR1 at mid-scale. Adjust 33 r.p.m. potentiometer 1VR1 so that 33 r.p.m. stroboscope dial appears to be standing still.

Set 45 r.p.m. potentiometer 4VR2 at mid-scale. Adjust 45 r.p.m. potentiometer 1VR2 so that 45 r.p.m. stroboscope dial appears to be standing still.

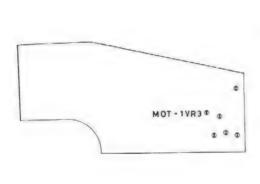
Adjustment of Slow Slide Transport

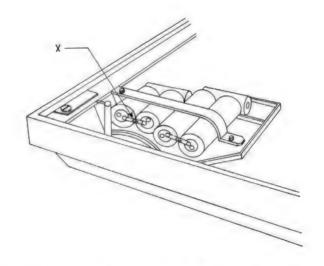




Connect a vacuum-tube voltmeter across the DC motor at M. Set vacuum-tube voltmeter at mid-scale and switch to 10-volt range. Applying light pressure to the in-transport panel (FO), adjust 1VR5 (FO) until the vacuum-tube voltmeter reads between 2.5 and 3.0 volts Adjust 1VR6 (RE) so that a similar reading in the opposite direction is obtained when the transport panel (RE) is pressed lightly.

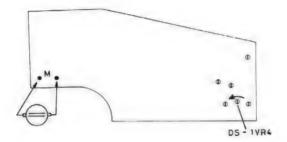
Adjustment of Voltage for Drive Motor





Connect AF voltmeter and oscilloscope at point X so that measurement is made with respect to chassis (0). In the 33 r.p.m. position, adjust potentiometer 1VR3 for maximum voltage though not more than 6.5 volts r.m.s. or approx. 18 volts p-p and so that distortion does not occur.

Adjustment of Differential Stop



Connect oscilloscope with disabled D-deflection across the motor at M.

Run the slide in so that MV contacts are operated.

Lower the arm before the run-off groove is reached on a 17 cm record.

Adjust potentiometer 1VR4 so that the stop releases when motor voltage is 1.8 volts.

Thereafter make sure that the stop releases on a 30 cm record.

LUBRICATION

The need for relubrication is very little. The instructions below should be followed for overhauls and replacement of important mechanical parts.

Bearing for arm 195 Bearing for arm 198	Everyman oil
Bearing for arm 205	3984211
Spindle 224	
Bearing for turntable 100	
Damper cylinder 255	Dow coming
	200 fluid
	3984214
Spring 192	
Spring 199	
Shaft 60	Beacon Q
Bearing for spindle 122	3984210
Shaft for position giver 227	
Under pointer 229	

FAULT-FINDING SYSTEMATICS

Testing and Fault-finding Diagram

The diagram is composed by means of four symbols.



A circle denotes an activity that must be carried out in order for the test to continue.



A square standing on end contains a question that must be answered with yes or no, thereafter continuing in the direction of the answer, Y or N.



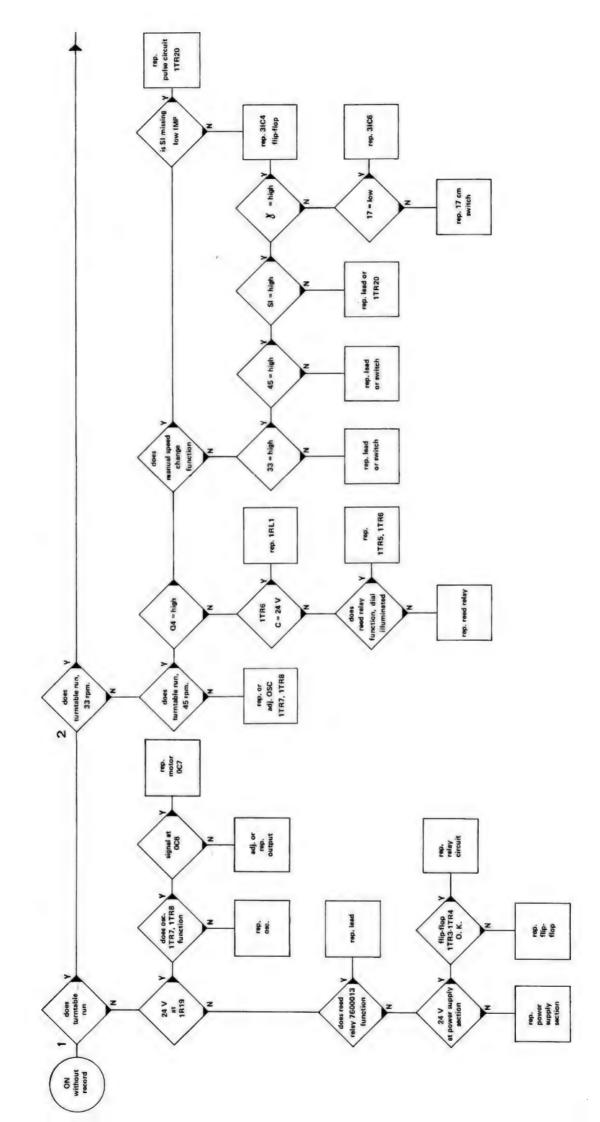
This square gives the designations of the main components of the circuit to be repaired.

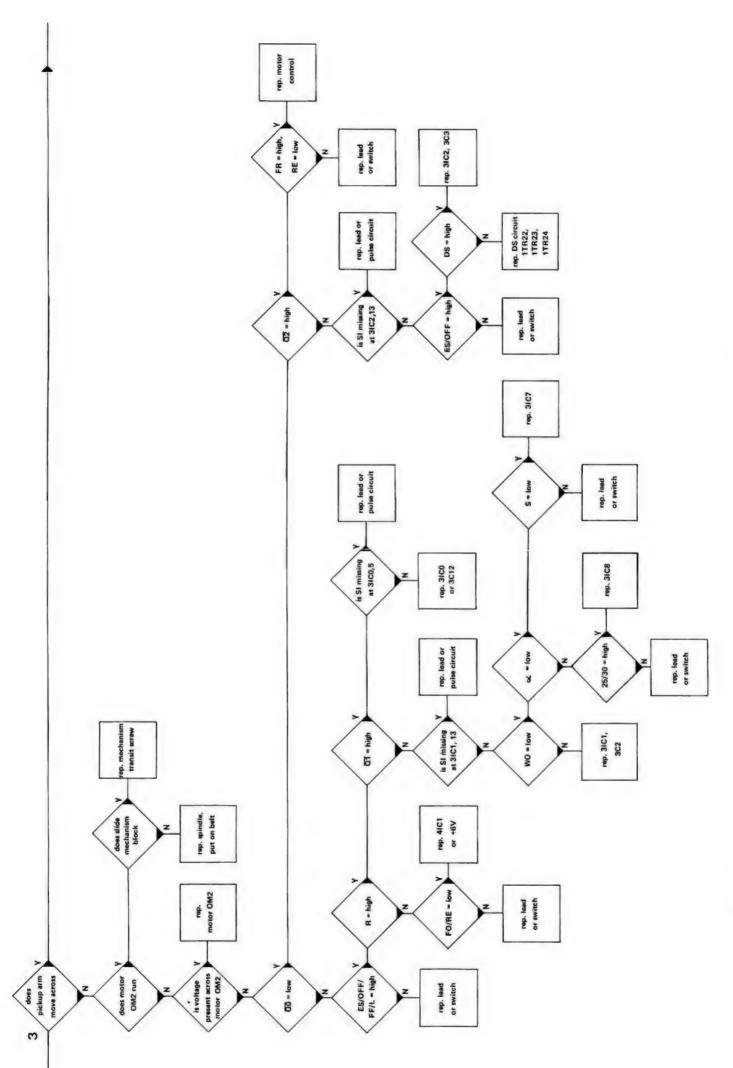


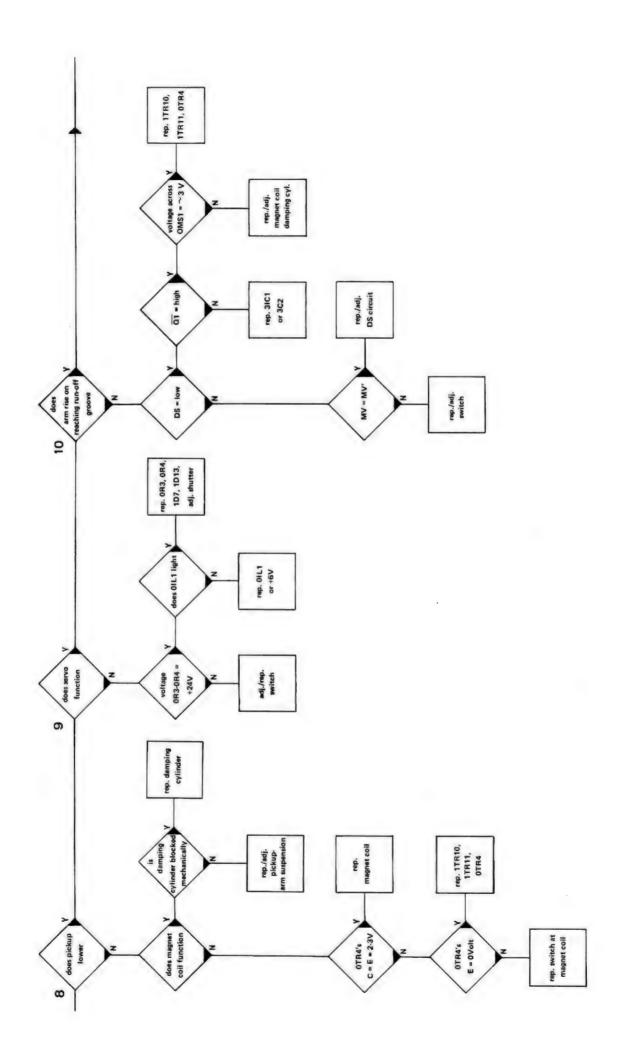
A triangle refers to a previous section.

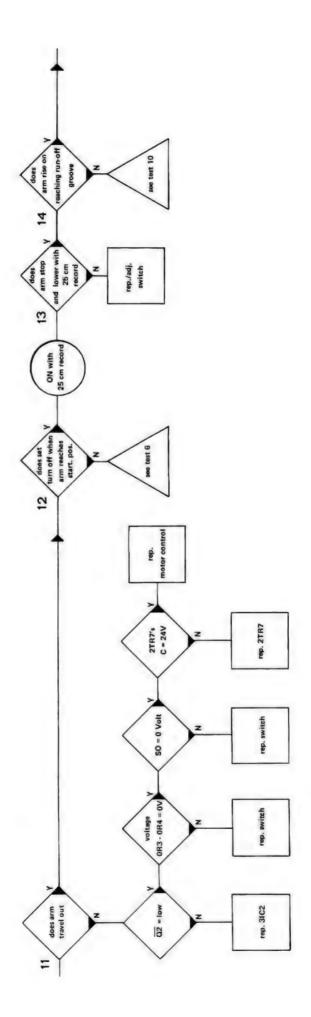
The question in the preceding square is found in the section to which reference is made, thereafter continuing in the direction of Y or N.

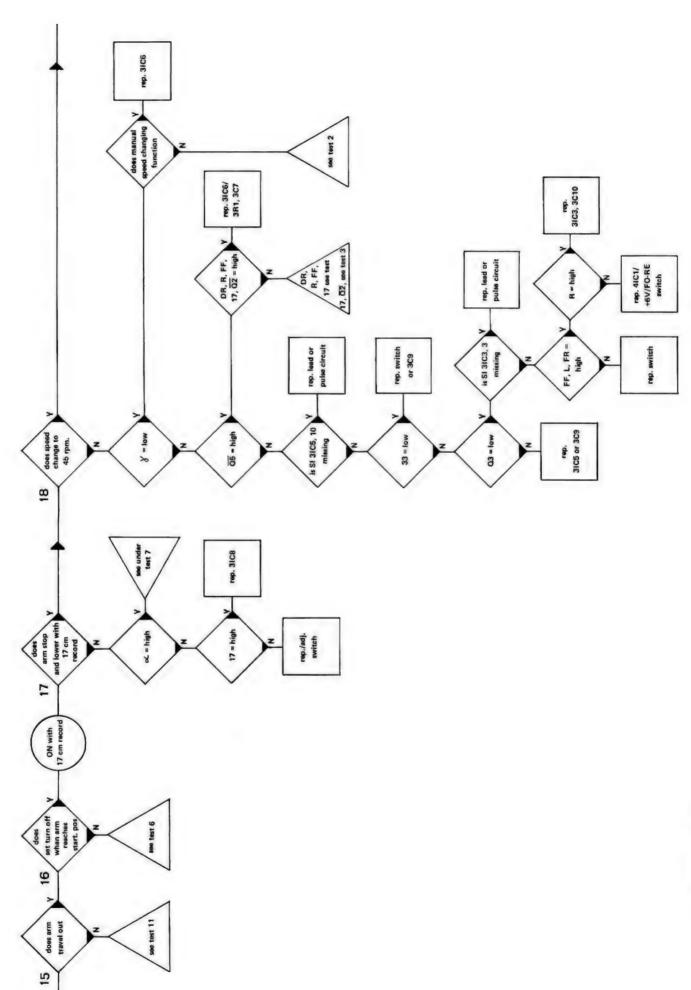
If the top horizontal line can be traced without encountering a no-answer, the controlling fonctions of the set will be O. K.

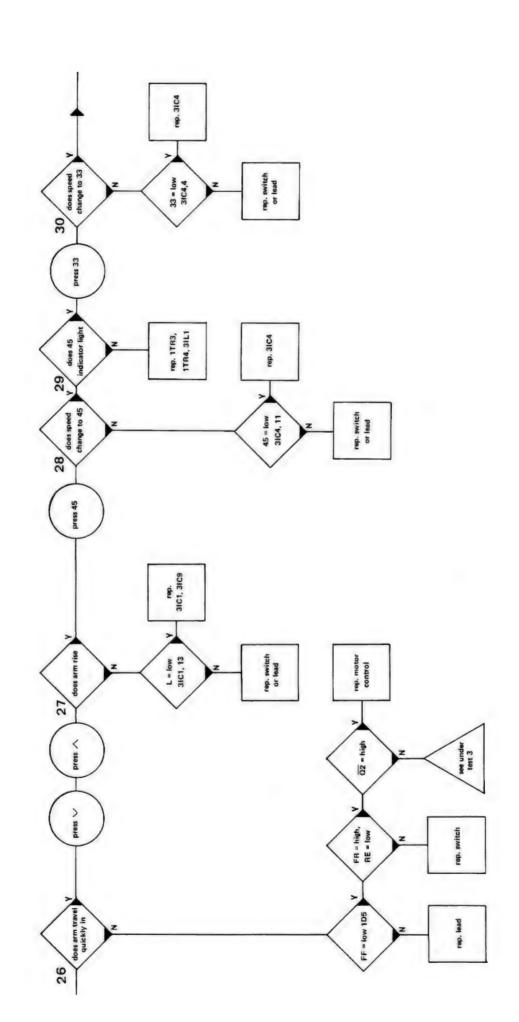


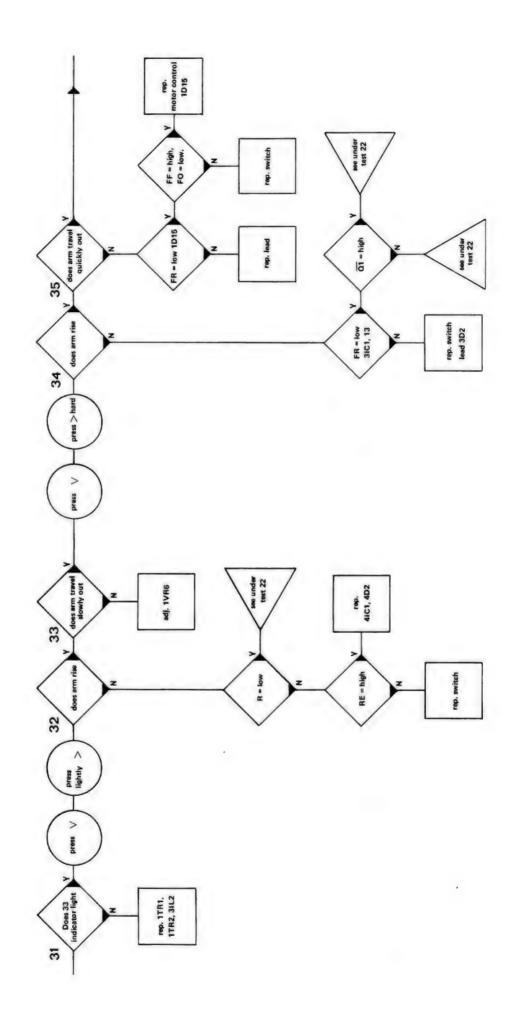




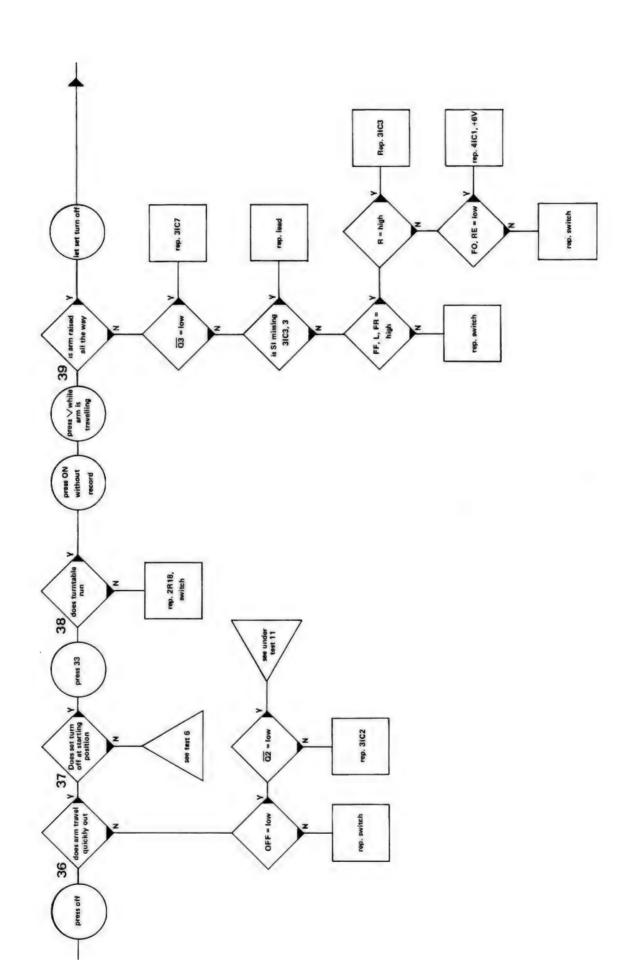


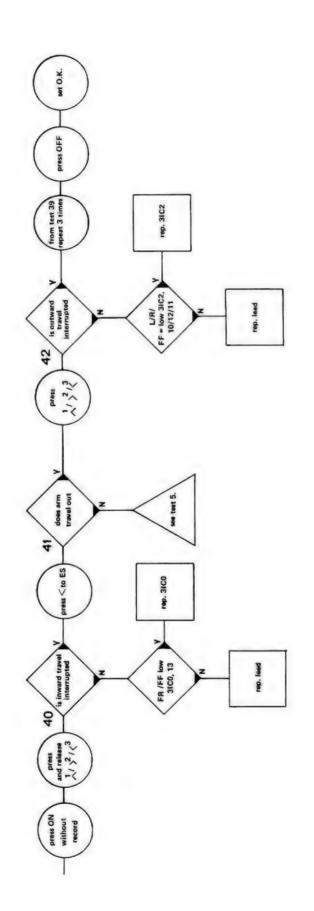


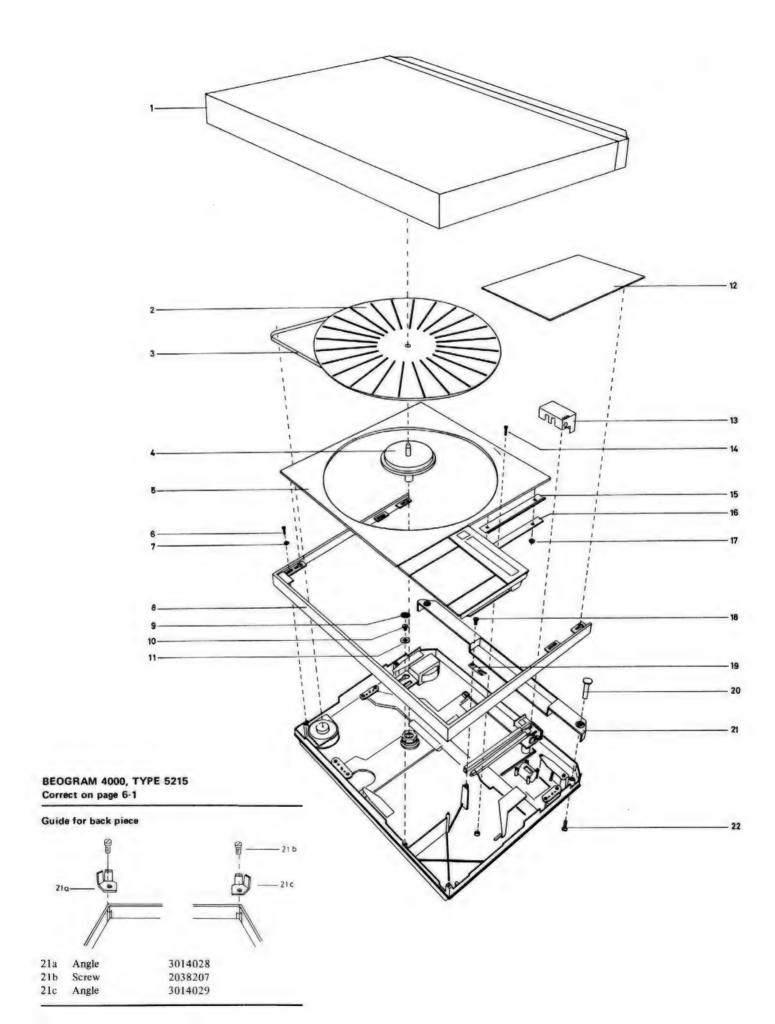


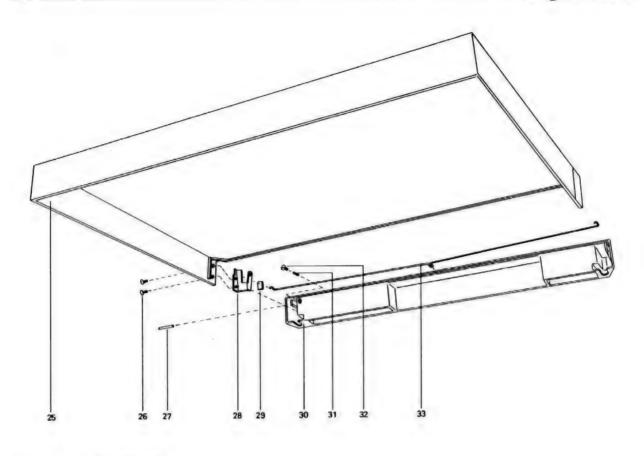


2









NOTATER / NOTES / NOTIZEN	

PARTS LIST FOR BEOGRAM 4000, TYPE 5215

see p	bage 6-1	
1	3164121	Dust Cover
2	2726054	Turntable
3	2732018	Belt
4	2726047	Turntable
5	3458081	Top plate
6	2038009	Screw AM 3 X 8 DIN 63
7	2803004	Washer
8	3411701	Cabinet, teak
	3411703	Cabinet, rosewood
	3411704	Cabinet, oak
9	3912037	Felt washer
10	2038901	Screw
11	2620019	Washer
12	3458080	Top plate
13	3164142	Cover
14	2038216	Screw AM 3 X 10 DIN 84
15	2816085	Spring
16	3014023	Guide plate
17	2380093	Nut M 3
18	2042201	Screw AM 4 X 4 DIN 84
19	2816083	Holder
20	2994012	Bushing
21	3452143	Back plate
22	2042216	Screw AM 4 X 16 DIN 84
25	3164113	Dust cover
	3010007	Stop
	2560036	Decorative list
26	2038055	Screw AM 3 X 6 DIN 63
27	2830014	Bearing needle
28	3030023	Mounting hardware, left
	3030022	Mounting hardware, right
29	3015030	Guide rail
30	3452145	Back plate
31	2072704	Threaded pin
32	2038050	Screw AM 3 X 4 DIN 63
33	2819062	Spring

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· ·

40	3458092	Dial
41	2775224	Pushbutton
42	2775177	Pushbutton
43	2816067	Spring
44	3152063	Circuit board holder
45	8009016	PC board
46	3030021	Holder
47	3151079	Clamp
48	8009015	PC board
49	2038206	Screw AM 3 X 4 DIN 84
50	2834022	Shaft
51	2812040	Spring
52	2775176	Pushbutton
53	3114050	Chassis
	3322034	Mirror
54	2380011	Nut M 3
55	2038206	Screw AM 3 X 4 DIN 84

see page 6 - 6

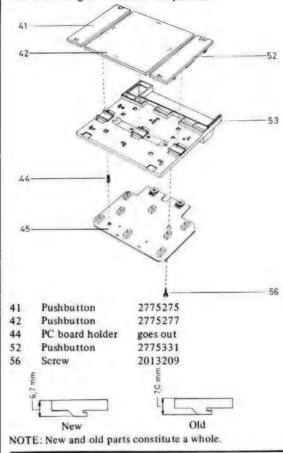
**	2005045	Daniero
59	2905045	Bearing
60	2830049	Shaft Screw AM 3 X 10 DIN 84
61	2038216	
62	8009011	PC board
63	2072710	Threaded pin
64	2380094	Nut
65	2042211	Screw, AM 4 X 12 DIN 84
66	3014021	Holder
67	2628005	Spring
68	2381008	Nut
69	2993024	Threaded pin
70	2038233	Screw AM 3 X 20 DIN 84
71	2038214	Screw AM 3 X 8 DIN 84
72	7530008	Solder tag
73	2510089	Clamp
74	2510090	Clamp
75	4200265	El. capacitor
76	4200260	El. capacitor
77	4200259	El. capacitor
78	4200258	El. capacitor
79	2038207	Screw, AM 3 X 5 DIN 84
80	2622041	Washer
81	3114042	Chassis
82	3014022	Belt guide
83	2038239	Screw AM 3 X 35 DIN 84
84 *	8400061	Motor
	2722010	Pulley
	3151117	Mounting hardware
	2038055	Screw AM 3 X 6 DIN 63
	2038208	Screw, AM 3 X 5 DIN 84
85	2938074	Rubber bushing
86	2381007	Nut
87	2628005	Spring
88	8300160	Diode
89	5012011	Resistor
90	7530045	Solder tag
91	3172027	Insulating piece
92	3170047	Mica sheet
93	8320103	Transistor
94	3164027	Cover
95	2034215	Screw AM 2 X 8 DIN 84
96	2038206	Screw AM 3 X 4 DIN 84
97	2938097	Insulating bushing
98	8320266	Transistor
	8320265	Transistor
	8320312	Transistor

* Concerning motor with topmounting see page 6-8

BEOGRAM 4000, TYPE 5215 Correct on page 6-4

Pushbutton system

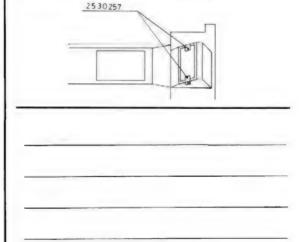
The pushbutton system has been modified so that PC pos. No. 45 is screwed to chassis 53. Also, pushbuttons and pins have been modified. This results in the following corrections to the parts list:

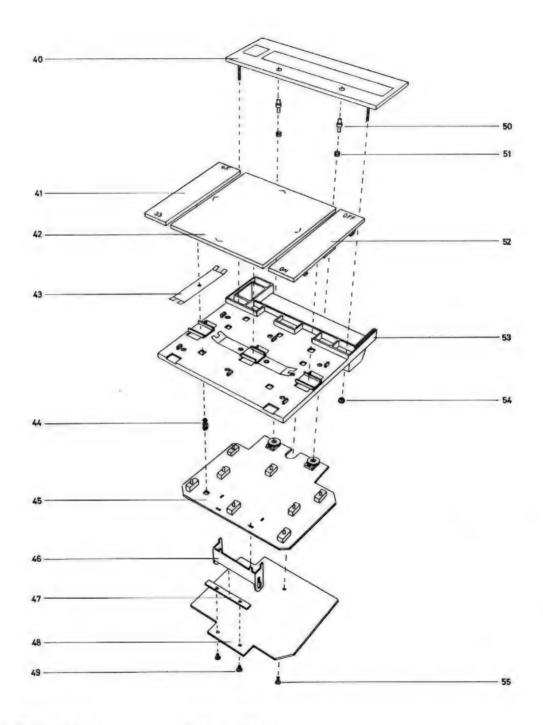


BEOGRAM 4000, TYPE 5215 Correct on page 6-4

Mirror, pushbutton chassis

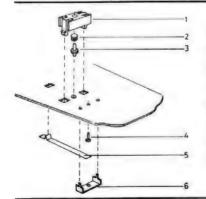
In order to secure better fastening of the mirror, two angles have been introduced which are glued on.



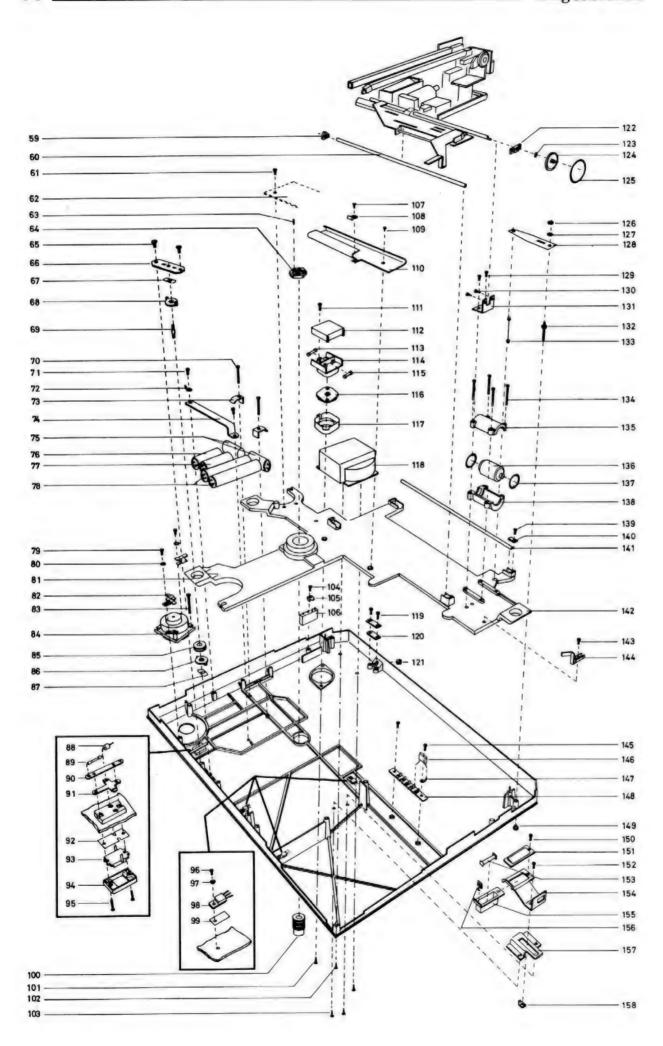


BEOGRAM 4000, TYPE 5215

Correct on page 6-4



Pos.	33	FF	45	S	L	ON	FR	OFF
1.	3152068	3152068	3152068	3152068	3152068	3152068	3152068	3152068
2								
3	7500067	2992051	7500067	2992052	7500067	7500067	2992051	7500067
4		2364024		2364024			2364024	
5	7500051	7500051	7500051	7500051	7500051	7500051	7500051	7500051
6	7500061	7500050	7500061		7500061	7500061	7500050	7500061



beginning on page 6 - 4

99	3170121	Mica sheet
100	2905046	Bearing
101	2013012	Screw 2,84 X 12,7 ART 4260
102	2013002	Screw ART 4260 2.84 X 6.35
103	2038055	Screw AM 3 X 6 DIN 63 Screw AM 3 X 6 DIN 84
104	2038209	Bracket
105	2574043 8310020	Rectifier B 80 C 2200
107	2013200	Screw Art 4261 2.84 X 6.35
108	2510091	Lead holder
109	2013002	Screw Art 4260 2.84 X 6.35
110	3013017	Lead holder
111	2038214	Screw AM 3 X 8 DIN 84
112	3164109	Cover
	3180607	Sticker
113	6600000	Fuse
114	3131060	Fuscholder
115	6600000	Fuse
116	7401001	Mains-voltage switch
117	3131050	Housing
118	8013107	Mains transformer
119	2038216	Screw AM 3 X 10 DIN 84
120	0287155	Clamp
121	2938077	Rubber bushing
122	2905034	Bearing
123	2620027	Washer
124	2722008	Pulley
	2070701	Threaded pin
	2380068	Nut
125	2732016	Belt
126	2380016	Nut
127	2622022	Washer
128		Spring Screw AM 3 X 4 DIN 84
129	2038206	Screw AM 3 X 4 DIN 84
130 131	2038206 2530253	Bracket
131	2072914	Screw
133	3955022	Suspension
134	2038235	Screw AM 3 X 25 DIN 84
135	3131048	Housing
136	8400062	Motor
130	2722005	Pulley
137	2732015	Rubber disc.
138	3131048	Housing
139	2038216	Screw AM 3 X 10 DIN 84
140	2644003	Clamp
141	2830045	Shaft
142	3114042	Chassis
143	2038206	Screw AM 3 X 4 DIN 84
144		Bracket
145	2038208	Screw, AM 3 X 5 DIN 84
146	4130087	Capacitor
147	7530005	Solder tag
148		Tagstrip
149		Plastic foot
150		Screw AM 3 X 8 DIN 84 nylon
151	3375017	Cover Screw, AM 3 X 6 DIN 84
152		Neon lamp
153 154	8230038 3151092	Holder
134	3131092	Mirror
155	3131058	Housing for neon lamp
156	7500064	Contact spring
157	3151090	Holder
158		Nut
100	2007000	

BEOGRAM 4000, TYPE 5215 Correct on page 6-7

Servobelt

As from unit No. 157700, a triangular belt has been introduced instead of the previous round one.

This results in the following corrections to the parts list:

124	Pulley	2722015
125	Belt	2732032
136	Pulley	2722016

The belt and pulleys constitute a whole.

Holder for neon lamp (154)

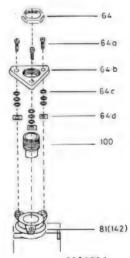
Two mouldings as shown by the sketch have been introduced in current production. They are glued on.



Moulding

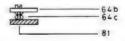
3950229

Disc bearing (tiltable)



64	Nut	2380096
64a	Screw	2038216
64b	Cap	2641076
64c	Washer	2624027
64d	Plastic spire	2390020
100	Bearing	2905046
81	Chassis	3114066

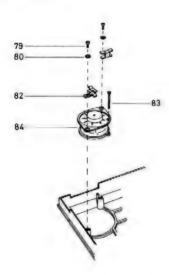
Washers 64c should be mounted as shown by the sketch.



124 Pointed screw 2072921

Correct on page 6-7 to be continued on page 6-8

Motor with topmounting



79	2038207	Screw, AM 3 X 5 DIN 84
80	2622041	Washer
82	3014022	Belt guide
83	2038239	Screw, AM 3 X 35 DIN 84
84	8400046	Motor
	2722007	Pulley

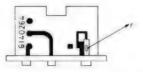
Not shown parts

6271048	Mains lead
6270010	Pickup cable with plug
3535024	Instruction diagram
3391384	Outer carton
3391385	Top/bottom inserts
3397157	Packing, foam insert, lid
3397158	Packing, gable insert, left
3397159	Packing, gable insert, right

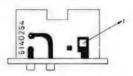
BEOGRAM 4000, TYPE 5215 Correct on page 6-7

Transformer

118 Transformer 8013131 214 PC unit 8009013



PC unit belonging to transformer 8013107: When



substituting transformer 8013131 it is necessary to replace PC unit 8009013. See sketch.

Drive motor

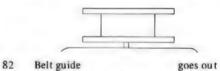
Drive motor with mounting

8400061 bushings 8400066

Drive motor less bushings

Both motors are equipped with drive bushing

2722010

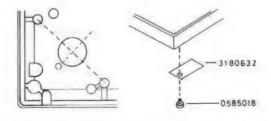


BEOGRAM 4000, TYPE 5215 Correct on page 6-8

Drive motor

When replacing motor 8400046 with motor 8400061, a 20 mm dia. hole must be drilled in the bottom to accommodate the shaft and bottom bearing.

After having installed the motor, affix sticker 3180632 over the hole in the bottom.



see page 6-11

170	2038206	Screw AM 3 X 4 DIN 84
171	3151084	Chassis
172	2390004	Circlip
173	2812037	Spring
174	7500058	Spring
175	2389030	Nut
176	7500057	Spring
177	2038247	Screw, AM 3 X 6 DIN 84
178	7530005	Solder tag
179	2072918	Threaded pin
180	3151086	Holder
181	2816074	Spring
182	2072705	Threaded pin.
183	2038247	Screw, AM 3 X 6 DIN 84
184	3152076	Holder
185	2038208	Screw, AM 3 X 5 DIN 84
186	3391407	Transit protection device
187	2034236	Screw AM 2 X 3 DIN 84
188	7200022	Socket
189	3152088	Holder
190	3937808	Arm
191	2390004	Circlip
192	2810044	Spring
	6430026	Insulatiin
193	2034914	Screw AM 2 X 6 DIN 63
194	8760002	Fotoresistor
195	2853025	Arm
196	8230020	Lamp
197	3375018	Optics
198	2853026	Arm
199	2810024	Spring
200	6810001	Magnet coil
201	2850047	Shaft
202	2038948	Screw
203	2852022	Arm
204	2034236	Screw AM 2 X 3 DIN 84
205	2854022	Arm
206	2850052	Pickup arm
207	2034914	Screw AM 2 X 6 DIN 63 Screw AM 3 X 10 DIN 84
208	2038216	
209	2641075	Clamp
210	2072911	Threaded pin Pick-up unit
211	8905428	Service-kit for pick-up
212	3624008	
212	3302158	Cap Screw AM 3 X 4 DIN 84
213	2038206	PC board
214	8009013	
	7500051	Contact spring Rivet
	2364024	Washer
	2622002	Solder lug
215	7530040 2038948	Screw
215 216	2624021	Washer
217	2038206	Screw AM 3 X 4 DIN 84
217	8230025	Lamp
210	7201016	Socket

212	Cap for pick-up	3302230
Detec	ctor arm	
Solde	ered optics	
		gr
88, 197	Socket Optics	goes out 3375023
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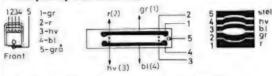
beginning on page 6-9

220	8009014	PC board
	7500051	Contact spring
	2364024	Rivet
221	2389031	Nut
222	2038208	Screw, AM 3 X 5 DIN 84
223	3152074	Holder
224	2993025	Spindle
225	2038206	Screw AM 3 X 4 DIN 84
226	2622041	Washer
227	2830046	Shaft
228	2390004	Circlip
229	3190053	Pointer
230	2644010	Cover
231	2812040	Spring
232	2798003	Eccentric
233	2819061	Spring
234	2851062	Arm
235	2812041	Spring
236	2390004	Circlip
237	2894029	Shaft
238	2802023	Washer
239	2038233	Screw AM 3 X 20 DIN 84
240	2072705	Threaded pin
241	2034231	Screw AM 2 X 4 DIN 84
242	2854023	Arm
243	2390004	Circlip
244	3342020	Counterweight
245	3152089	Holder
246	2390046	Circlip
247	2070400	Threaded pin
248	3150032	Bearing holder
240	2900003	Ball bearing
	2622168	Washer
	2812036	Spring
	2390047	Circlip
249	2700008	Adjustment bearing
250	2834038	Shaft
251		Shaft
252	2361018	Locking pin
253	2622167	Washer
254	2038206	Screw AM 3 X 4 DIN 84
255	3131059	Damper cylinder
256	2038222	Screw AM 3 X 14 DIN 84
257	3164112	Cover
258	2854024	Diaphragmarm
259	2013203	Screw 2.84 X 12.70 ART 4261
260	3131052	Housing
200	5210004	Fotoresistor
261	3151085	Holder
262	2038946	Screw
263	2794029	Roller
	2622041	Washer
264	2038208	Screw, AM 3 X 5 DIN 84
265 266	2798003	Fecentric
267		Chassis
201	3114046	Sticker for transport screw
	3180536	
	2038946	Screw
0-0	2620028	Rubber disc
268	2625003	Tooth-lock washer
269	2380016	Nut
270	2510086	Bracket
271	6140272	PC board
272	2038206	Screw AM 3 X 4 DIN 84

BEOGRAM 4000, TYPE 5215 Correct on page 6-10

Pick-up arm

The pick-up arm has been modified so that the leads from the pick-up socket are soldered directly to the PC on pick-up arm holder 245.



 206
 Pick-up arm, assembled
 2850073

 244
 Counterbalance weight
 3342030

 245
 Holder
 3152160

When replacing pick-up arm 2850052 with pick-up arm 2850073, counterbalance weight 3342020 must be replaced with counterbalance weight 3342030.



BEOGRAM 4000, TYPE 5215 Correct on page 6-10

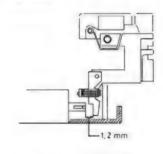
Stylus force spring (250)

The stylus force adjustment mechanism has been modified so that the shaft, spring, and gearwheel are mounted without use of glue. The mechanism is supplied in kit form under index No. 2834041.

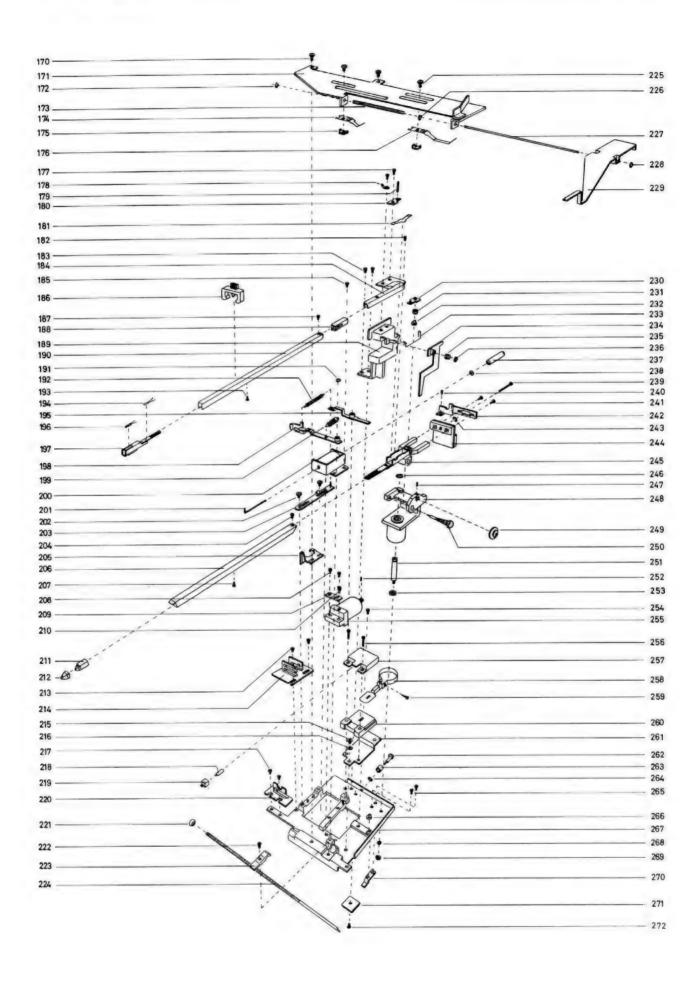
Leads, pick-up arm

248 Wire bundle (copper wire) 6300059

Arm 234, adjustable



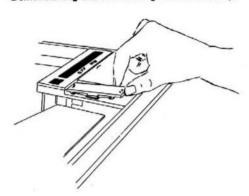
234	Arm complete	2851083	
234a	Screw	2034219	
234b	Arm complete Screw Spring	2812065	

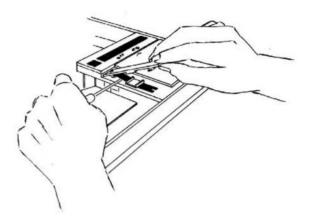


SERVICE TIPS

Demontering og montering af trykknap
Dismounting and mounting of pushbutton

Demontierung und Montierung vom Druckknopf

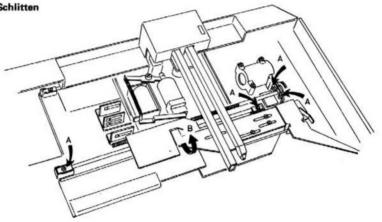




Demontering af slæde

Dismounting of slide

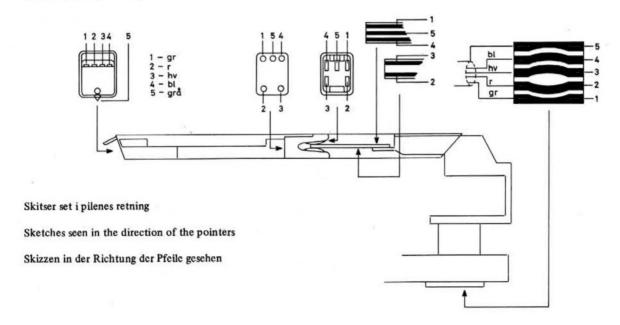
Demontierung vom Schlitten



Ledningsmontering i pićk-up arm

Mounting of cable in the pick-up arm

Montierung einer Leitung im Tonabnehmerarm



ISSUE NO. BG1.

GLOUCESTER

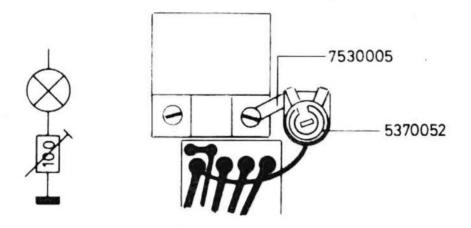
2ND JANUARY 1974

BEOGRAM 4000

Servo system adjustment.

The sensitivity of the servo system corresponding to 15-19 record grooves deviation away from the record centre has until now, been adjusted by pushing the diaphragm up and down, which varies the amount of light falling on the photo resistors. This adjustment has become difficult because of tolerances in the sensitivity of the photo resistors and the light output of the bulb.

In order to overcome this a potentiometer of 100.0 has been put in series with the lamp OIL1; this adjusts the brightness of the bulb and therefore the sensitivity of the servo system.



ISSUE NO. BG2.

GLOUCESTER

2ND JANUARY 1974

BEOGRAM 4000 Type 5215

Servo drive belt

Because of difficulties in supply of the original round belt, a triangular belt has been introduced. This gives the following corrections to the parts lists:

Pos.	124	Pulley	2722015
Pos.	125	Belt	2732032
Pos.	136	Pulley	2722016

When replacing the earlier belt or pulley all three parts mentioned above must be replaced at the same time due to differences in design.

The modification has been introduced in production from S.N. 157700.

* * * * * * * * * *

ISSUE NO. BG3.

GLOUCESTER

6TH MAY, 1974

BEOGRAM 4000 Type 5215

Detector arm circuit

In order to improve the life expectancy of the lamp in the detector arm, a new bulb is used, part number 8230047. Since this lamp has a lower consumption and light output than its predecessor it has been necessary to make minor changes to the BL and DR circuits.

BL circuit

The lower lamp consumption can result in insufficient voltage being developed across 1R30 to operate 1TR12 reliably. Therefore, 1R30 is changed from 15 ohms to 22 ohms, part number 5011004.

DR circuit

Since the new lamp has less intensity it is necessary to remove the 50K potentiometer mounted on the print side of the PW board. This, it will be remembered, was installed to give a measure of control over the sensitivity of the DR circuit for dealing with semi-transparent records and is not shown in the circuit diagram.